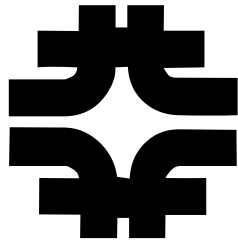


On Tevatron Tune Fitter/Tracker, Status Reports and Plans



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Fermilab

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The team...

- *Jim Patrick, Charlie Briegel, Ron Rechenmaker* for Control and D.A. software
- *Dean Still, Charlie Briegel* HP3561a installation & support, access to VSA tune data.
- *John Marraffino*, offline software and ROOT interfacing
- *Vladimir Shiltsev, & TeV dept*, for their support and patience in MCR..

Outline

- Goal and Scope of this project.
- Brief description Algorithm used in fitting, and C++/Java implementation.
- Examples of fits
- Can this method be used at ~ 20 Hz instead of a fraction of 1Hz ?
 - Yes, based solely on ad-hoc convolution and simple extremum detection.
 - Test algorithm written, performance O.K., need data !
- *Note :By not too distant training, I am a High Energy Physics, Accelerator Physics is something new exciting. \rightarrow expect some naïve ideas/statements!.*

Tevatron Tune Tracking: Goal & Scope

Written January 30 2003.. *Edited this week.*

- Automatic fits of the Tune Spectrum Analyzer data seems a difficult task, as it is just a mess of broad bump, narrow signals, and “mostly noise” (especially for coalesced beams)
- Goal of a Tune Meter : express “the art of picking the right line” into a reproducible algorithm that can be implemented on a modern computer, and can be run at ~ 1 Hz.
 - To improve the overall reliability of such measurements. ***Done***
 - Reduce clock time to doing such measurements ***Not demonstrated, real chance it will happen***
 - Allow the implementation a tune tracker, based a straight feedback loop using this tune meter. **To be considered**

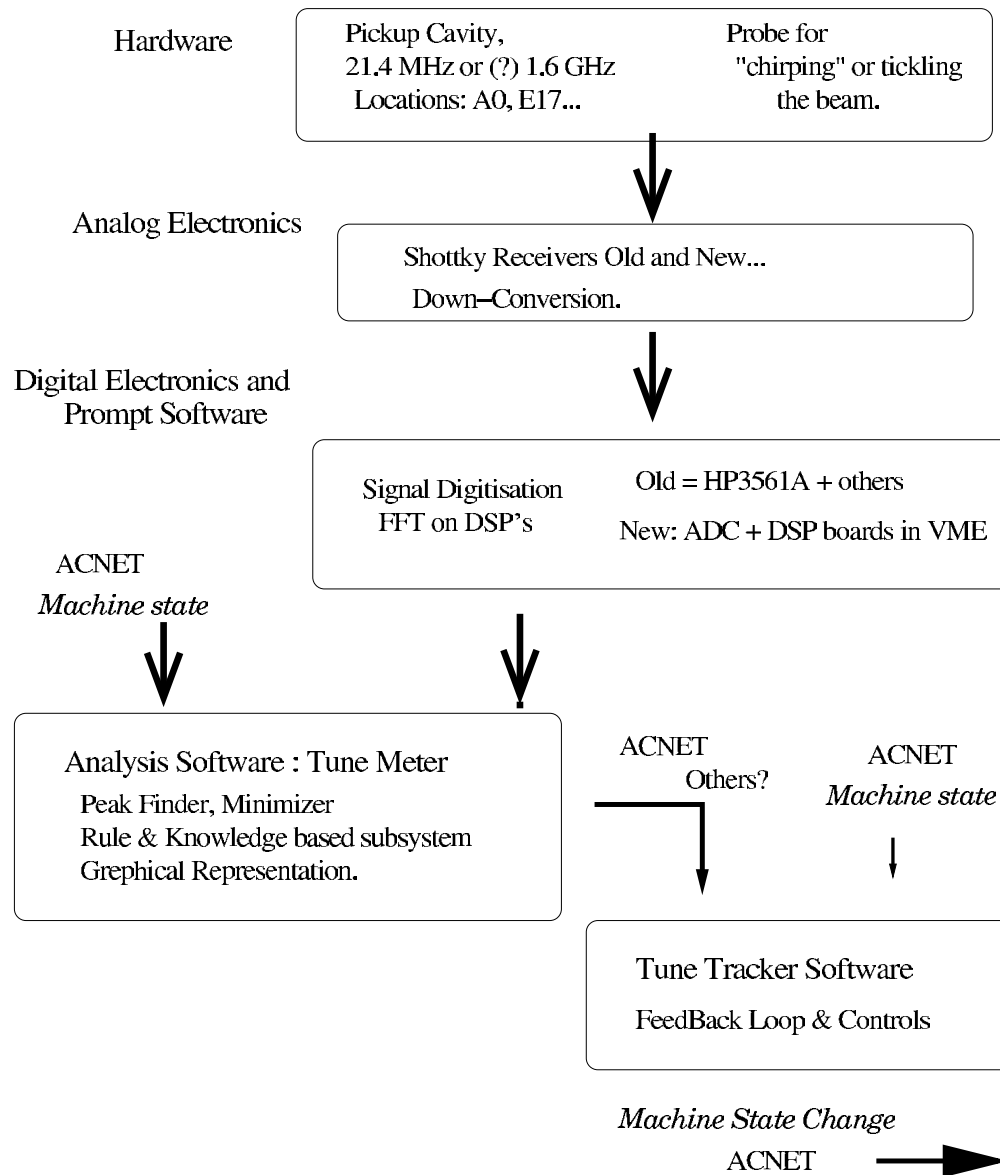
Tevatron Tune Tracking: Goal & Scope

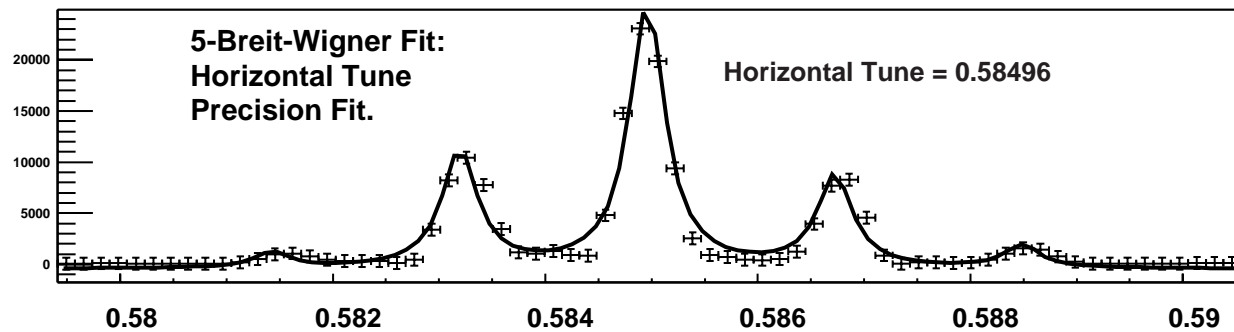
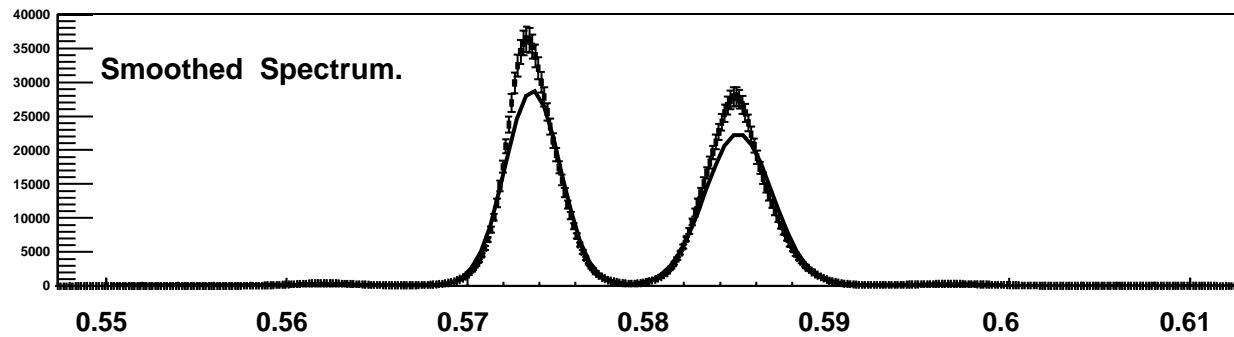
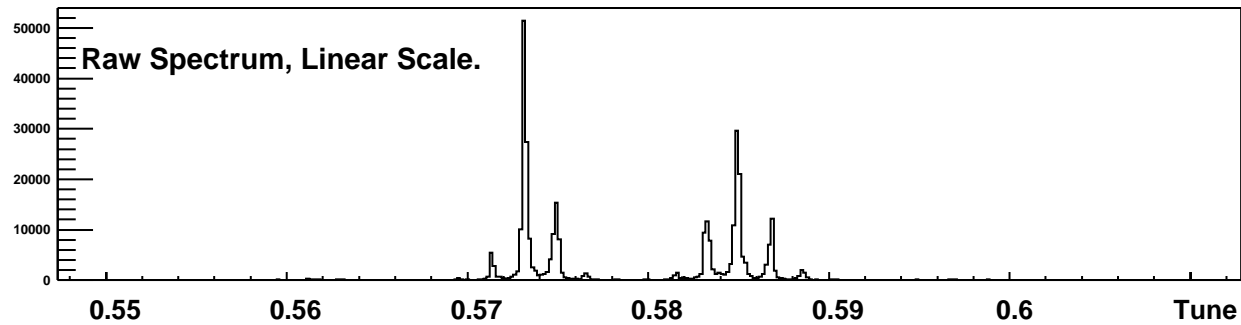
Written January 30 2003.. *Edited this week., II*

– Scope:

- Short term: Using existing equipment, (21.4 MHz Shottky, HP3561a) and new software (C++, Java, Root,..) ***Done, v1.0***
- Long Term: dedicated Front-end subsystem with better digitization and FFT on DSP, refine analysis software... ***Under Construction....***

Tune Meter/Tracker : A simplified "System" View

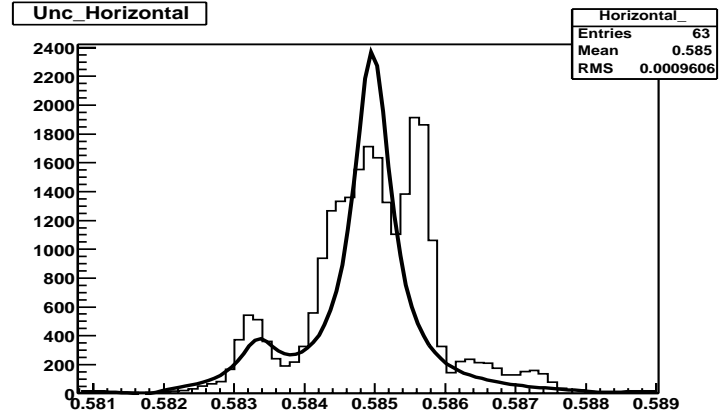
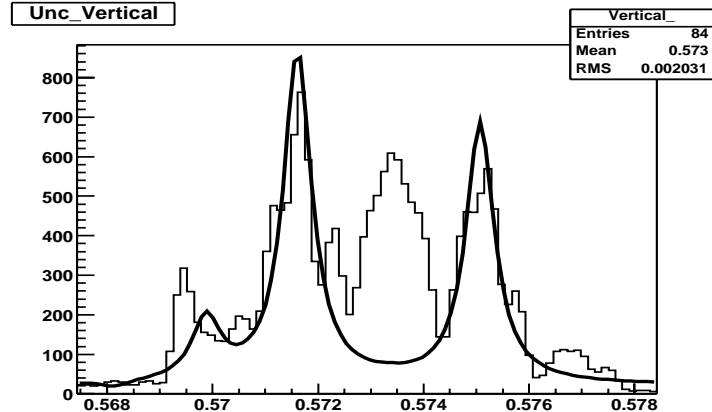
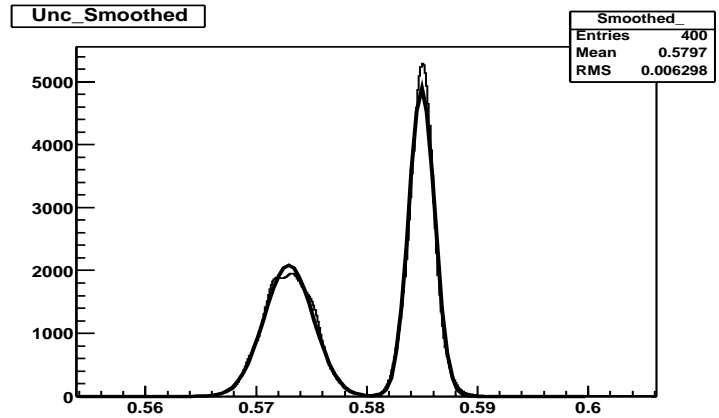
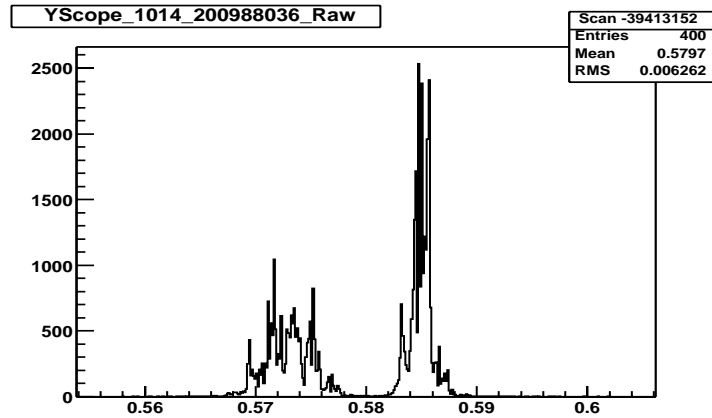




Algorithms..Uncoalesced..

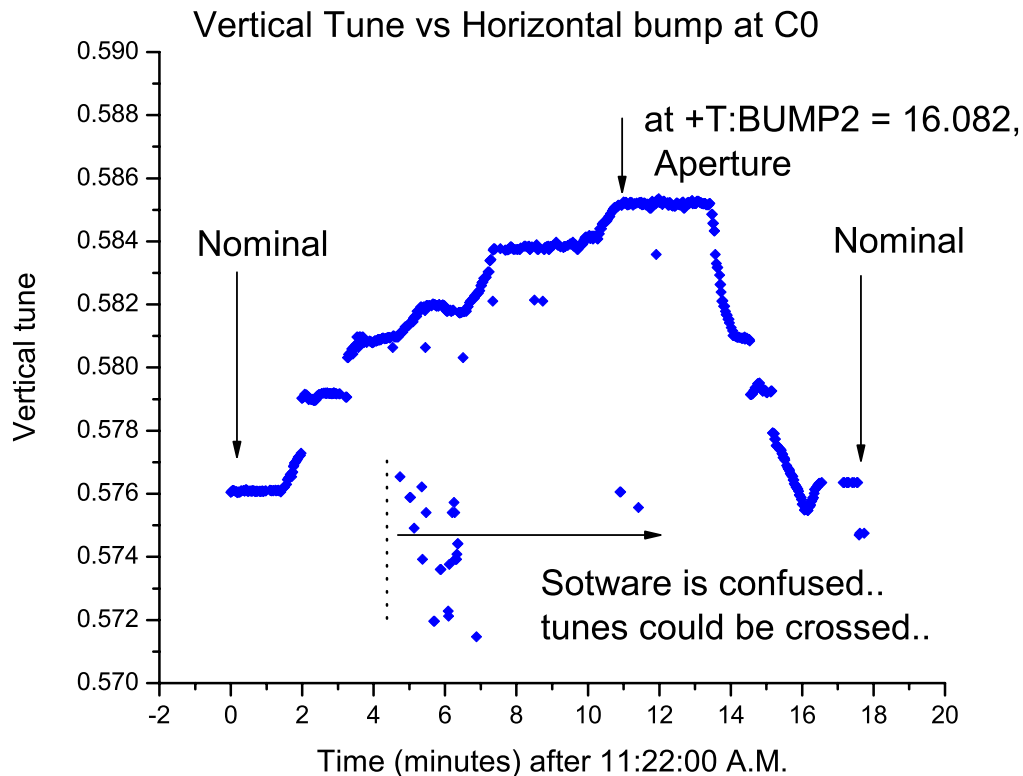
- First, Histogram, on a linear Y scale.
- Scale such the noise level (~ -80 to 70 db) corresponds to few counts per bin.
- Smear (or smooth), on a big scale: every bin content is spread, Gaussian wise, to neighboring bins. This is just a Gaussian convolution or “transform”
- Fit Two Gaussians. This determines the broad value of the Horizontal and Vertical tunes.
- Make two distinct new histograms, one for each region, using the original data.
- Smooth, Cern algorithm, two times.
- Fit with 5 Breit-Wigners, with same widths and same frequency splitting between satellites and main line.

Spectrum as “Things Change.” 23:04, Dec 11



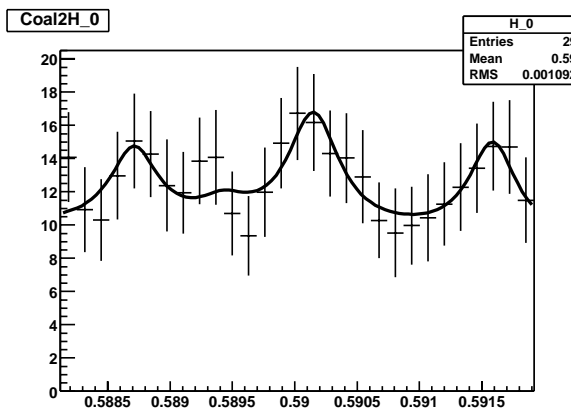
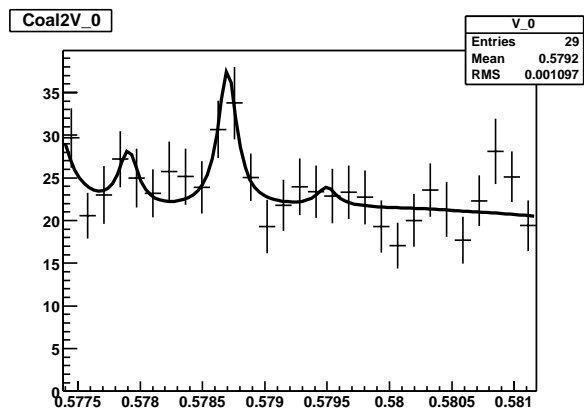
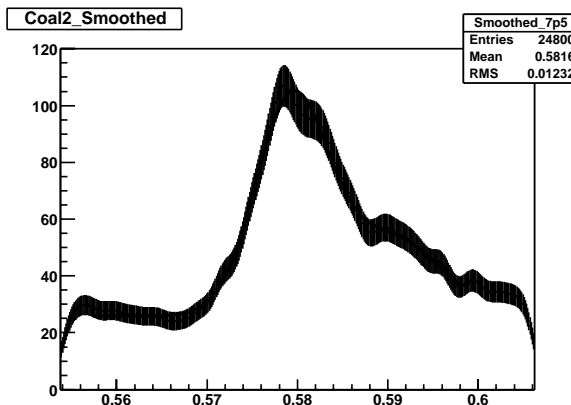
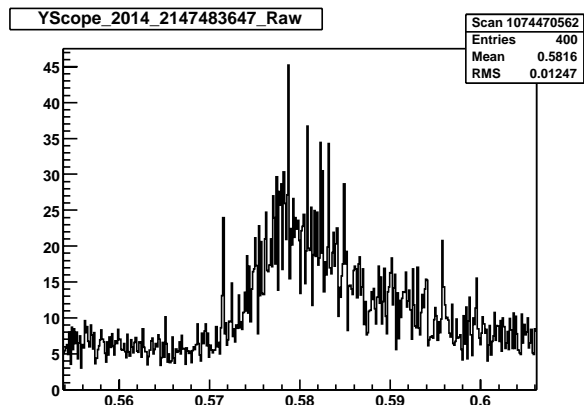
Despite missed bumps, Synch split, $H = 0.0017312$, $V = 0.0016207$, Predicted = 0.00166

Vertical Tunes vs Bump position at C0 (Parasitic)



- **Very sensitive to horizontal position.**
- **Caveat (again) : tunes did cross while doing the scan and the software is confused.**

Coalesced, p-bar beams is much harder!



- Data taken on Dec. 16 2002, 11:38 A.M. (store 2078, ~ 2 hours into the store).
- Nothing but noise lines at this point???
- There is more than one tune !
- How do we establish a signal?
- Note : these lines are clearly beam related!

Fast Algorithm: From a fraction of 1Kz to ~ 20 Hz.

- 1 Hz not quite good enough with respect to changes occurring during the ramp, if this fitter ought in a feed-back loop.
- Can a passive system, with a fast tune fitter work, work for the Tevatron : Yes, it should work. At 20 Hz, or faster..
- The question is: will be it be precise enough? It can't work better than $\sim 2 \pi (20 \text{ Hz}/27 \text{ KHz}) \sim 4.5 \cdot 10^{-3}$ The convolution process will make it worse by (?) $\sqrt{2}$ at best..
- Which is not quite good enough for the Run II TeV, given our limited dynamic aperture and relatively large betatron coupling (min. tune split of ~ 0.003), and the constraints from lattice (We run at $(\nu_x - n_y) \sim 0.009$)
- *Yet, we should try to speed-up these fitting algorithms!! It is a good idea...*

A Fast Algorithm: Determine the extremum of a Gaussian Convolution of the signal.

- If guaranteed speed is an issue, “real time” would be nice.
- If “real-time”, fixed – or almost fixed – number of operations!.
- A single convolution with fixed parameters might work..
 - Two embedded loops: for all channels, amplitude is an integral
 - Inner loop limited
 - fixed coefficients in sum in this inner loop.
- Then, once convoluted, don’t fit, simply look for the extremum (a) .
 - Using numerical derivative to locate the extrema That’s the tune location. It works, provided the noise frequency is high enough with respect to the convolution parameters. If many “tunes” => more extrema..
 - Keep only two of them.. Use “knowledge” to select them if more than two.
- Extremum search is in the top level loop.. => loop once over all channels. Integrate, differentiate, select -> done.

A Fast Algorithm: Implementation & Performance.

- *In C++*
- *Can be optimized..*
- *On a Sun “not from too distant past”*
- *From 400 channels, takes 1 mSec to fit the previously shown “Uncoalesced” spectrum ...*
- *Same speed on Coalesced, but less precision..*

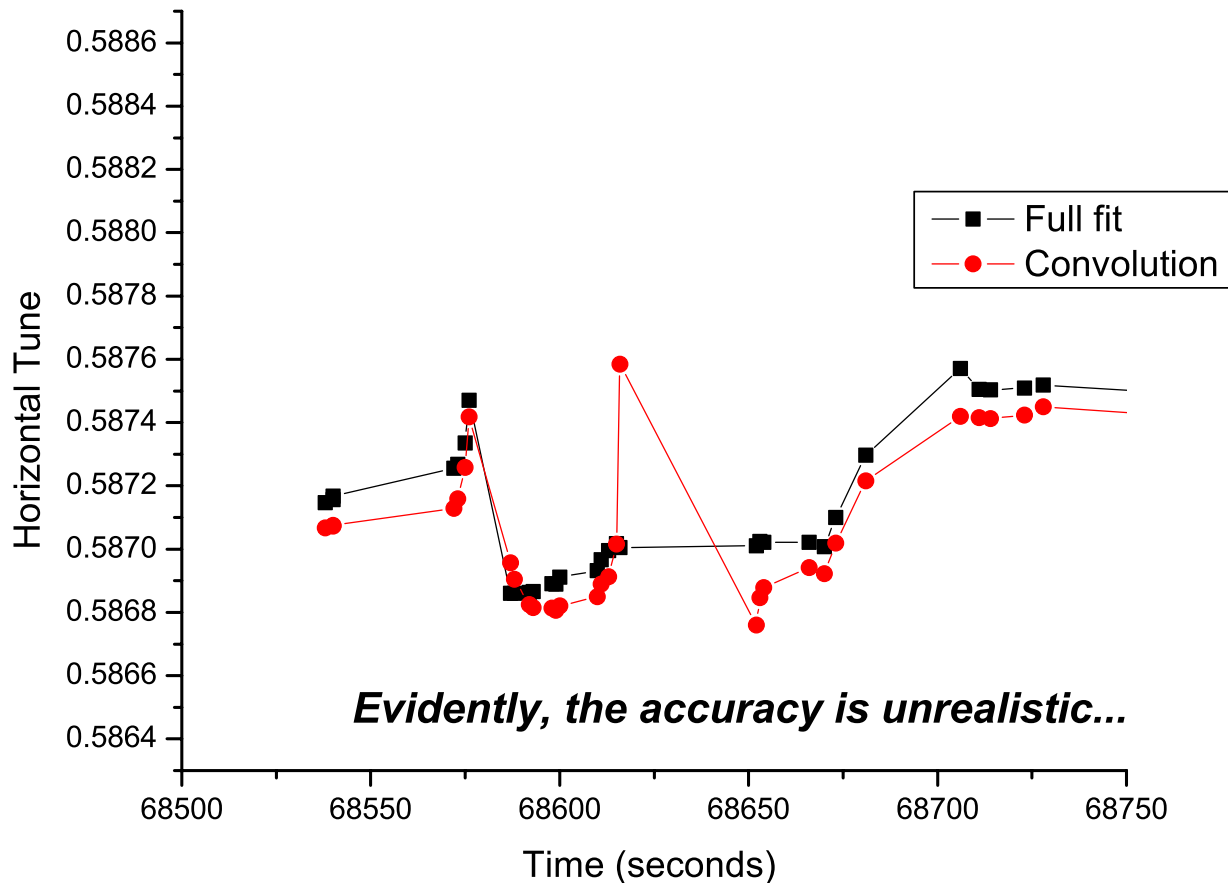
A Fast Algorithm: Code - I

```
• for (int i=((int) nBinSmooth)/2; i< (len - ((int) nBinSmooth) + 1); i++) {  
•     int iStart = i - i3;  
•     int iStartW = 0;  
•     if (iStart < 0) {  
•         iStartW = -iStart;  
•         iStart = 0;  
•     }  
•     int iEnd = i + i3;  
•     if (iEnd > len) iEnd = len; // Should not be needed  
•     double val = 0.;  
•     int iW=iStartW;  
•     for (int k=iStart; k<iEnd; k++) {  
•         val += dataIn[k]*weights[iW];  
•         iW++;  
•     }  
•     double deriv = val - prevVal;  
•     // Now we look for an extremum, if we are at leas one sigma convol  
•     // away from start  
•     if (i < nBinSmooth) {  
•         prevVal = val;  
•         prevDeriv = deriv;  
•         continue;  
•     }  
• }
```

A Fast Algorithm: Code , II

```
.    if ((val > minValForTune) && ((deriv*prevDeriv) < 0.)) {
.        // Refine the tune, by fitting to a parabola.
.        // Use the fact that we equal bin spacing, so that the
.        // quadratic equation can be linearized
.        double y3 = val;
.        double y2 = prevVal;
.        double y1 = y2 - prevDeriv;
.        double dx0 = binWidth * 0.5*(y3-y1)/(2.0 * y2 - y3 -y1);
.        double tune = tuneBin0 + (i-1)*binWidth + dx0;
.        if (debugIsOn) {
.            *rollingLog << " Tentative tune at  " << tune << endl;
.            *rollingLog << " y1 " << y1 << " y2  " << y2 << "  y3  " << y3 << endl;
.        }
.        if (abs(tune-tunePrevSet) > minTuneSep) {
.            if (debugIsOn) *rollingLog << " Valid extremum  " << endl;
.            extrFound = true;
.            if (tuneLowSet && (abs(tune-tunePrevHigh) < maxTuneJump) ) {
.                tuneHigh = tune;
.                amplHigh = val;
.                if (debugIsOn) *rollingLog << " Tune High set at  " << tune << endl;
.            } else if (abs(tune-tunePrevLow) < maxTuneJump){
.                if (debugIsOn) *rollingLog << " Tune Low set at  " << tune << endl;
.                tuneLowSet = true;
.                tuneLow = tune;
.                amplLow = val;
.            } else if (abs(tune-tunePrevHigh) < maxTuneJump){
.                if (debugIsOn) *rollingLog << " Tune High set at  " << tune << endl;
.                tuneHigh = tune;
.                amplHigh = val;
.            }
.        }
.    }
.    prevVal = val;
.    prevDeriv = deriv;
. }
```


Preliminary test on 1 Hz data from HP3561a..



This study must be repeated with the correct data, from a digitizer/FFT system.. M. Huening is building such a system.

Digital Solutions..

- Numerical Gaussian Convolution and differentiation could be done with analog hardware .. Mixing.. Filtering! High-band pass filter... Or low-band.. Who cares...
- Because digital are intrinsically more maintainable, tunable and robust than advanced analog solution.. (*Bill Foster, May 7, Run-II Commisioning meeting...*)
 - Case in point: Easy to clone this system running at a different rate (10 Hz instead of 20), from the same signal!). And this can be done in //. No “cross-talk” between individual componenent.
- Evidently, we need to think in both time-domain (“Real time computing” and “frequency domain” (FFT over finite range of frequencies..).

Status

- The code runs on data generated by the Hp3561a..
- Need to try this on data from the fast digital ADC/DSP + FFT spectrum analyzer, at ~ 20 Hz.
- Our first priority, though, is to integrate the existing software to the TeV control system, so that we can use the tune fitter to automate Chromaticity and coupling measurement.